

Numerical solution of ordinary differential equations

DE-1

Differential equation: function + its derivatives in the equation.

e.g. $f'(x) = g(f(x), f'(x), \dots, x)$

Order: highest derivative

Ordinary: univariate partial: multivariate

Linear: $f(x)$, derivatives on the first power, no multiplication

Homogeneous: no parts with x or constant

More functions: set of differential equations

General solution: integration + constant

$$f(x) = \int f'(x) dx + C$$

Particular solution (initial condition: $f(x_0)$ known)

$$f(x) = \int_{x_0}^x f'(x) dx + f(x_0)$$

Boundary conditions: \rightarrow eigen problems often

Old time: analytical sol. Nowadays: numerical

Higher order can be rewritten to first order ones, e.g.:

$$f''(x) + f'(x) + q(x) = 0$$

$$g(x) = f'(x)$$

$$g'(x) = g(x) - q(x)$$

Methods using one starting point

Explicit Euler method:

$x_0 \rightarrow x_f$ interval

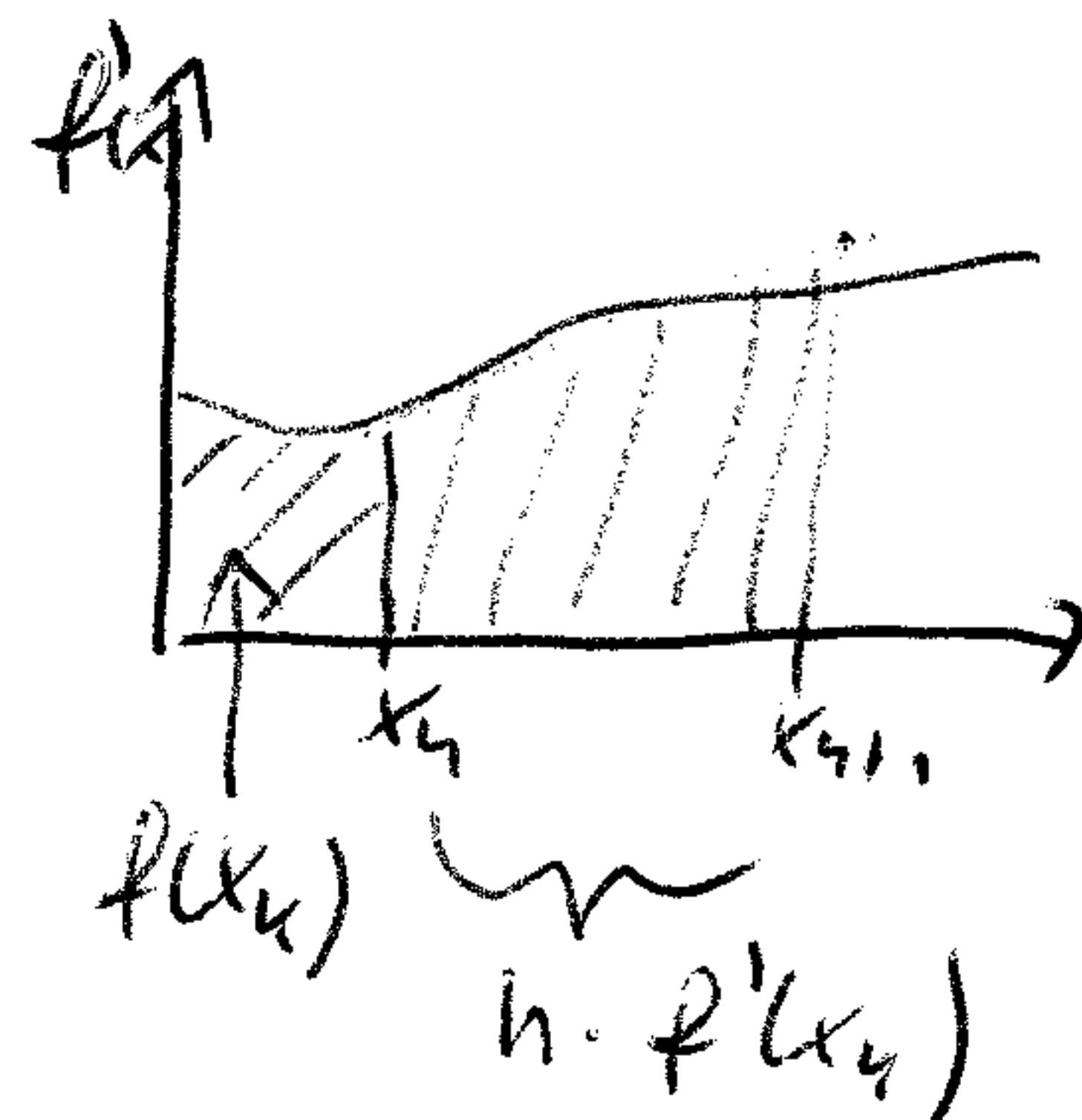
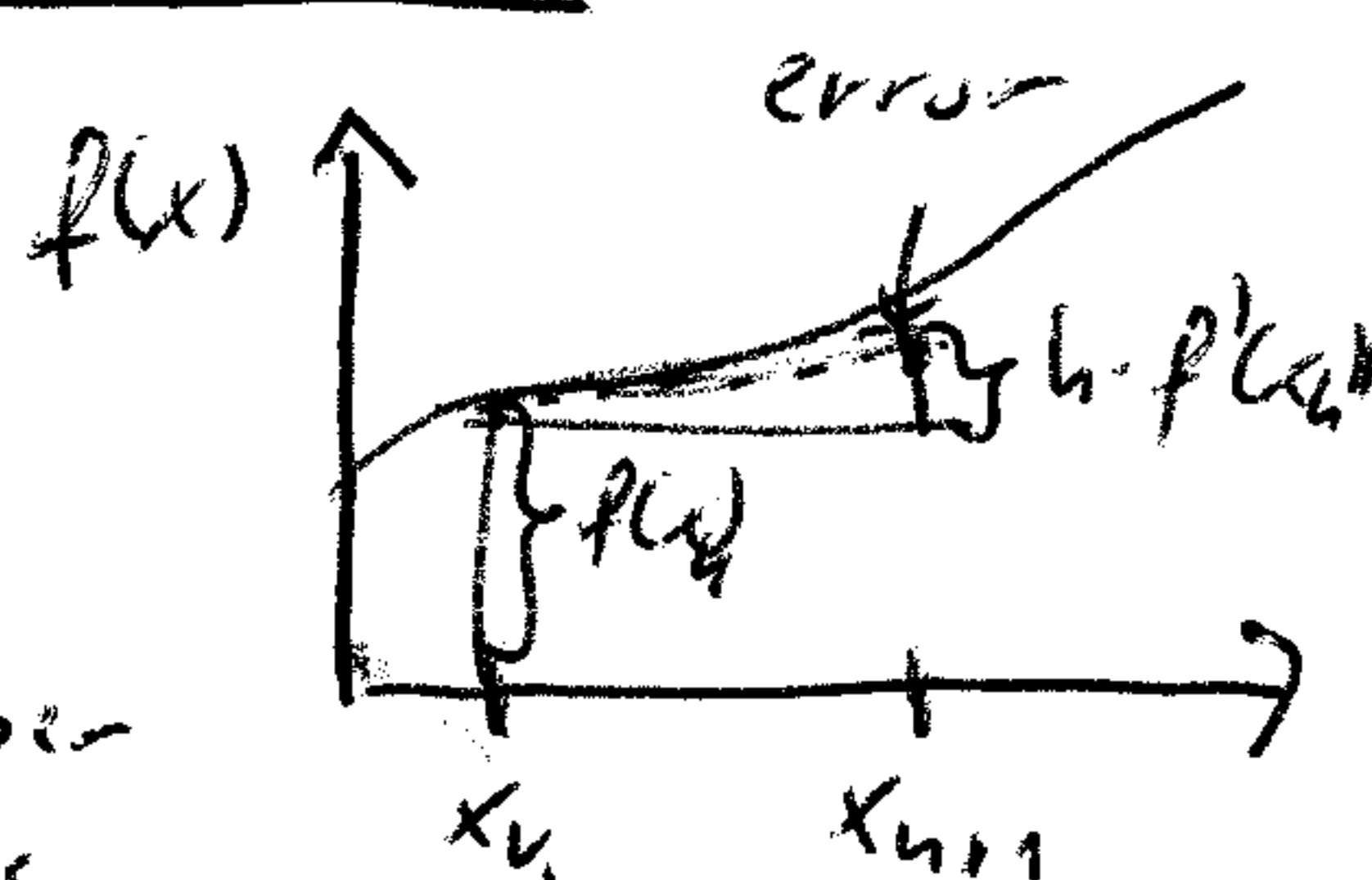
h step size

$$h = \frac{x_f - x_0}{n}$$

n = number of steps

$$x_{k+1} = x_k + h$$

$$f(x_{k+1}) = f(x_k) + h \cdot f'(x_k)$$



$$\text{error: } \underbrace{\tilde{f}(x_{n+1})}_{\text{real}} - \underbrace{f(x_{n+1})}_{\text{calculated}} = \underbrace{\Delta f(x_n)}_{\text{error in previous steps}} + \underbrace{\Delta(f(x_n) \rightarrow f(x_{n+1}))}_{\text{local step}}$$

explicit Euler is bad!

global error

Runge-Kutta methods

$$y_{i+1} = f(x_{i+1})$$

use linear combination of different provisional steps

$$y_{i+1} = y_i + h \cdot \sum a^{(n)} \cdot f^{(n)}(x_i + \alpha^{(n)} \cdot h; y_i + \beta^{(n)} \cdot h)$$

e.g. RK2 - improved Euler

$$k_1 = h \cdot f'(x_i, y_i)$$

$$k_2 = h \cdot f'(x_i + h, y_i + k_1)$$

$$y_{i+1} = y_i + \frac{1}{2}(k_1 + k_2)$$

RK4 - (trapezoidal version)

$$y_{i+1} = y_i + k_1/6 + k_2/3 + k_3/3 + k_4/6$$

$$k_1 = h \cdot f'(x_i, y_i)$$

$$k_2 = h \cdot f'(x_i + \frac{h}{2}, y_i + k_1/2)$$

$$k_3 = h \cdot f'(x_i + \frac{h}{2}, y_i + k_2/2)$$

$$k_4 = h \cdot f'(x_i + h, y_i + k_3)$$

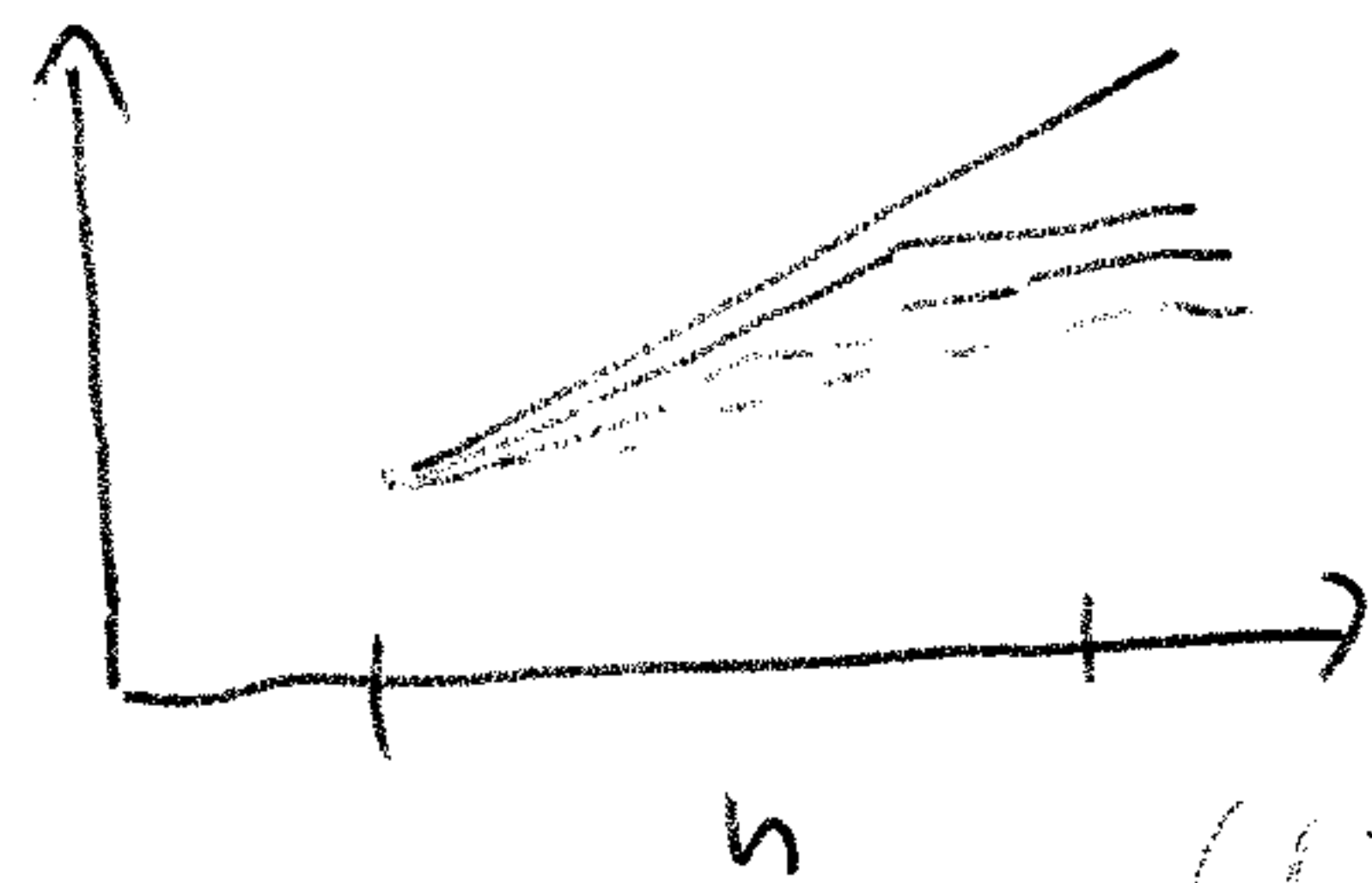
there are other "tangential" forms.

How to determine h ? \approx error? (repeat with $h/2$)

	global error	local error	no. $f(x)$ calculation
exp Euler	$O(h)$	$O(h^2)$	1
imp. Euler	$O(h^2)$	$O(h^3)$	2
RK4	$O(h^4)$	$O(h^5)$	4

Runge-Kutta-Fehlberg method for error:

Bulirsch-Stoer interpolation



do with $h, h/2, h/4, \dots$

↓
interpolate
to $h \rightarrow 0$

(like Runge's integration)
(later)

Methods using more starting points

x_{i-2}, x_{i-1}, x_i and y_{i-2}, y_{i-1}, y_i are known

↓
fit a parabolic curve there & Taylor expansion
(calculation of numerical derivatives backward)

3 point $\rightarrow 3-1=2$ order polynomial

e.g. Adams-Bashfort method:

$$y_{i+1} = y_i + \frac{h}{12} (23y'_i - 16y'_{i-1} + 5y'_{i-2}) + O(h^4) \quad *$$

implicit Euler:

$$y_{i+1} = y_i + h f'(x_{i+h}, y_{i+1})$$

↑
obtained by solving non-linear equations or
by rearrangement

more first "more" starting points can be got by RK4

predictor-corrector methods

e.g. Adams-Bashfort-Moulton

(1) $\tilde{y}_{i+1} =$ as * prediction & Taylor expansion

(2) $y_{i+1} = y_i + \frac{h}{12} (5\tilde{y}'_{i+1} + 8y'_i - y'_{i-1}) + O(h^4)$ correction

Many different predictor-corrector methods:

- weight of previous steps in correction

DE-4

- number of previous steps

- place of correction (e.g. impulse or acceleration)

↓
see e.g. Gear-methods and tables

Differential equation sets (ordinary ones)

- parallel solution in a reasonable order

e.g. $A(t)$, $B(t)$, $C(t)$ compounds, at first A, then B...

- total implicit schemes do not work (~~roots of~~ ^{in each step}
x root finding in multidimensions is dangerous

- semi-implicit works

$$f_3(x_{i+1}) = f_3(x_i) + h \cdot f_3'(f_1(x_{i+1}), f_2(x_{i+1}), \dots, f_3(x_i), \dots, f_n(x_i))$$

Stiff de sets

difference in the magnitudes, e.g.:

mechanics: small-large particles, weak-strong springs

reactions: fast and slow reactions

stat. mechanics: simulation of intramolecular/intermolecular motions

how to solve: - implicit methods

- more correction steps

- multi time step integrations

- adaptive (h varying) methods

Direct solution of second order differential equations: DE-5

Störmer-1907 (Verlet 1960)

$h = x - x_0$ forward and backward Taylor series

$$y(x_0+h) = y(x_0) + y'(x_0) \cdot h + \frac{1}{2} y''(x_0) h^2 + \frac{1}{6} y'''(x_0) h^3 + O(h^4)$$

$$+ y(x_0-h) = y(x_0) - y'(x_0) \cdot h + \frac{1}{2} y''(x_0) h^2 - \frac{1}{6} y'''(x_0) h^3 + O(h^4)$$

$$y(x_0+h) = -y(x_0-h) + 2y(x_0) + y''(x_0) h^2 + O(h^4)$$

symmetric for backward and forward

↑ (pred. corr. not symmetric!)

importance in physics, stat. physics